

# Model Building in Grand Unified Theories

Tomás Gonzalo

University College London

15 October 2014

Motivation

Review of Grand Unified Theories

Overview of Group Theory

Model Building

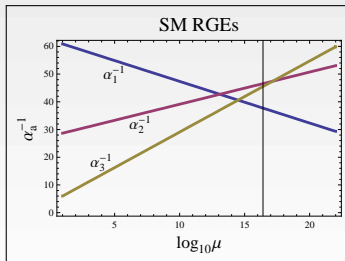
Groups and Representations

Theories and Models

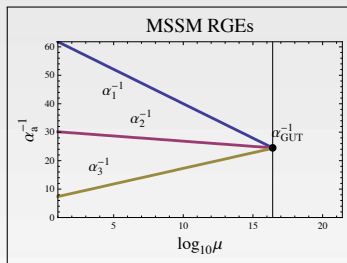
Conclusions and Applications

- The Standard Model of Particle Physics is not the ultimate theory
- Among its shortcomings it fails to explain the several phenomena, such as gravity, neutrino masses, dark matter, dark energy, etc
- There must be an extension of the Standard Model that can explain some of these observations
- We expect to see something new at the LHC in the next run

- Grand Unified Theories are among the best ways to extend the Standard Model, by enhancing its internal symmetries
- The partial unification of gauge couplings in the SM is a hint to a model such as this

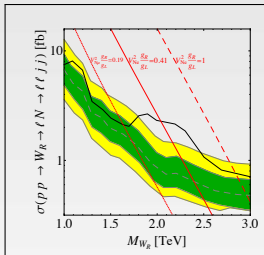


- If one includes low energy Supersymmetry, at the TeV scale, for example, the running gauge couplings is modified in such a way that the unification is even more evident



- Modulo some threshold corrections, Supersymmetric predicts the unification scale to be at  $M_G \sim 2 \times 10^{16}$ , which incidentally is high enough to be consistent with current bounds on proton decay.

- Grand Unified Theories are even motivated from the preliminary results from the LHC experiments



- CMS has found a peak on the  $pp \rightarrow lljj$  cross section, maybe corresponding to a  $W_R$  of around 2.2 GeV. The signal is only about  $2.8\sigma$  as of today, but it turns out to be confirmed, it would be the first evidence for a GUT, in particular a Left-Right symmetric model.

- However, the vast amount of different GUT models, with different representations and breaking paths makes it hard to match the phenomenology with the theory
- We argue that a tool that may take care of most of the model building chaos, discriminating among models and identifying those that are viable representations of reality, will be quite useful.
- The goal will be to construct such a tool, in order to automatise the model building process, with a minimum set of inputs, providing different scenarios and models to choose from.

- In Model Building the ultimate goal is to build a theory that is consistent mathematically and physically.
- The starting point will be **Group Theory**
- We begin with a minimal set of inputs at high energies: the Lie Group of internal symmetries and the field content.

$$\{\mathcal{G}, \mathcal{R}_1, \mathcal{R}_2, \dots\}$$

- We will use group theoretical methods to build viable models



- The tool will generate all possible models from that set of inputs
  1. Breaking paths from  $\mathcal{G}$  to the Standard Model
  2. Set of fields/representations at every scale
- Models will be discarded if they don't satisfy some constraints, e.g., reproduce the SM at low energies

$$\begin{aligned}
 Q &\rightarrow (\mathbf{3}, \mathbf{2})_{\frac{1}{6}}, & \bar{u} &\rightarrow (\bar{\mathbf{3}}, \mathbf{1})_{-\frac{2}{3}}, & \bar{d} &\rightarrow (\bar{\mathbf{3}}, \mathbf{1})_{\frac{1}{3}}, \\
 L &\rightarrow (\mathbf{1}, \mathbf{2})_{-\frac{1}{2}}, & \bar{e} &\rightarrow (\mathbf{1}, \mathbf{1})_1, & & (\times 3) \\
 & & H &\rightarrow (\mathbf{1}, \mathbf{2})_{-\frac{1}{2}}
 \end{aligned}$$

## Review of Grand Unified Theories

- Extend the symmetries of the Standard Model, whose gauge group is:

$$\mathcal{G}_{SM} \equiv SU(3)_c \otimes SU(2)_L \otimes U(1)_Y.$$

- One needs a Lie Group, of rank  $\geq 4$ , that contains the SM group as subgroup,  $\mathcal{G} \supset \mathcal{G}_{SM}$ .
- The SM field content should be contained in representations of  $\mathcal{G}$  that satisfy the chiral structure and don't generate anomalies.

$$\sum_R \mathcal{A}(R) = 0 \tag{1}$$

- H. Georgi and S. Glashow proposed in 1974 the first unified model, using the simple group  $SU(5)$ .
- The SM matter field content is embedded univocally in two representations of  $SU(5)$ ,  $\mathbf{10}_F$  and  $\bar{\mathbf{5}}_F$ , in the following way:

$$\mathbf{10}_F \equiv \begin{pmatrix} 0 & u_3^c & -u_2^c & u_1 & d_1 \\ -u_3^c & 0 & u_1^c & u_2 & d_2 \\ u_2^c & -u_1^c & 0 & u_3 & d_3 \\ -u_1 & -u_2 & -u_3 & 0 & e^c \\ -d_1 & -d_2 & -d_3 & -e^c & 0 \end{pmatrix}, \quad \bar{\mathbf{5}}_F \equiv \begin{pmatrix} d_1^c \\ d_2^c \\ d_3^c \\ e \\ -\nu \end{pmatrix}$$

- And the Higgs field falls into the representation  $\mathbf{5}_H$ , together with a colour triplet.

- The  $SU(5)$  model is that predicts the precise charge quantisation present in the Standard Model.

$$\frac{Y(Q)}{Y(e^c)} = \frac{1}{6}, \quad \frac{Y(u^c)}{Y(e^c)} = -\frac{2}{3}, \quad \frac{Y(d^c)}{Y(e^c)} = \frac{1}{3}, \quad \frac{Y(L)}{Y(e^c)} = -\frac{1}{2}.$$

- Breaking of  $SU(5) \rightarrow \mathcal{G}_{SM}$  happens when the **24**-dimensional representation acquires a vacuum expectation value.
- It requires precise gauge coupling unification,  $g_3 = g_2 = g_1$ , at a scale  $M_G$ , which does not happen exactly in the SM.
- Yukawa coupling unification is needed as well, but it does not predict the right fermion masses at the renormalizable level.

- Non-SUSY  $SU(5)$  predicts rapid proton decay, which happens through the off-diagonal gauge bosons,  $X$ ,

$$\Gamma(p \rightarrow \pi^0 e^+) \sim \frac{\alpha^2 m_p^5}{M_X^4}, \quad \tau_{exp} > 10^{34} \text{ years.}$$

- Supersymmetric  $SU(5)$  improves the unification of gauge couplings, to happen precisely at  $M_G = 2 \times 10^{16}$ , and requires an extra Higgs representation,  $\bar{\mathbf{5}}_H$ . It is also compatible with proton decay.
- A successful non-supersymmetric model for  $SU(5)$  can be built, by enhancing the symmetry to  $SU(5) \otimes U(1)$ , and taken the "flipped" embedding.

$$u_i^c \leftrightarrow d_i^c, \quad e^c \leftrightarrow \nu^c, \quad \mathbf{1}_F \equiv (e^c).$$

- Next attempt for an unified model was by J. Pati and A. Salam, shortly after. It involved the semi-simple group  $SU(4)_c \otimes SU(2)_L \otimes SU(2)_R$ .
- The SM field content is embedded in  $(\mathbf{4}, \mathbf{2}, \mathbf{1})$  and  $(\bar{\mathbf{4}}, \mathbf{1}, \mathbf{2})$ .

$$(\mathbf{4}, \mathbf{2}, \mathbf{1}) \equiv \begin{pmatrix} u_1 & u_2 & u_3 & \nu \\ d_1 & d_2 & d_3 & e \end{pmatrix},$$
$$(\bar{\mathbf{4}}, \mathbf{1}, \mathbf{2}) \equiv \begin{pmatrix} d_1^c & d_2^c & d_3^c & e^c \\ -u_1^c & -u_2^c & -u_3^c & -\nu^c \end{pmatrix}.$$

- And the SM Higgs is a bi-doublet  $(\mathbf{1}, \mathbf{2}, \mathbf{2})$ .

- Breaking to the SM can happen in different steps, through one or more intermediate groups

$$SU(4)_c \otimes SU(2)_L \otimes U(1)_R,$$

$$SU(3)_c \otimes SU(2)_L \otimes SU(2)_R \otimes U(1)_{B-L}.$$

$$SU(3)_c \otimes SU(2)_L \otimes U(1)_R \otimes U(1)_{B-L}.$$

- The Higgs sector includes fields in the representations  $(\bar{\mathbf{10}}, \mathbf{3}, \mathbf{1})$  and  $(\bar{\mathbf{10}}, \mathbf{1}, \mathbf{3})$ , and the order in which they acquire v.e.v.s determines the breaking path.



- This model naturally includes the right-handed neutrino in the content, which requires some sort of Seesaw Mechanism to explain the hierarchy.

$$\mathbf{M}_\nu = \begin{pmatrix} 0 & m_D \\ m_D & M_R \end{pmatrix} \rightarrow \begin{cases} m_\nu \sim \frac{m_D^2}{M_R} \\ m_{\nu^c} \sim M_R \end{cases}$$

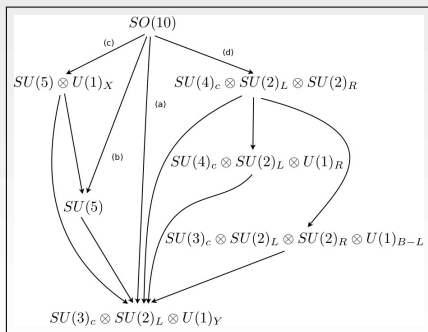
- There are three (two) different gauge couplings, so strict unification is not required, and thus this model can be satisfied in the non-supersymmetric scenario.
- Neither the gauge or scalar sectors induce proton decay, so it is possible to have some light states ( $\gtrsim$  TeV), maybe within reach of the LHC.

- The first model to have all the SM fermions unified in a single representation is  $SO(10)$  unification (H. Fritsch and P. Minkowski, 1975).
- The spinor representation,  $\mathbf{16}$  is not self conjugate, so it respects the SM chiral structure. A particular choice for the Clifford algebra gives the embedding

$$\mathbf{16}_F \equiv \{u_1, \nu, u_2, u_3, \nu^c, u_1^c, u_3^c, u_2^c, d_1, e, d_2, d_3, e^c, d_1^c, d_3^c, d_2^c\}$$

- The SM Higgs doublet (or both MSSM Higgs doublets) can be embedded in the  $\mathbf{10}_H$  representation, although an accurate prediction for fermion masses requires the addition of higher dimensional representations such as  $\mathbf{120}_H$  or  $\overline{\mathbf{126}}_H$ .

- $SO(10)$  contains maximally the subgroups  $SU(5) \otimes U(1)$  and  $SU(4) \otimes SU(2) \otimes SU(2)$ , so it favour from the advantages of both previous models.
- It can break directly to the SM, or through either of the maximal subgroups as intermediate steps.



- Another family unified group is  $E_6$ , which contains in its fundamental representation,  $\mathbf{27}$ , all the SM matter content, plus some Higgs multiplets and a singlet
- $E_6$  has the maximal subgroup  $SO(10) \times U(1)$ , under which the  $\mathbf{27}$  representation decomposes as

$$\mathbf{27} \rightarrow \mathbf{16}_1 \oplus \mathbf{10}_{-2} \oplus \mathbf{1}_4$$

- There is an alternative, and also quite interesting, embedding of the SM into  $E_6$ , which is through the subgroup  $SU(3)_c \times SU(3) \times SU(3)_w$ . And  $\mathbf{27}$  decomposes as

$$\mathbf{27} \rightarrow (\mathbf{3}, \mathbf{1}, \mathbf{3}) \oplus (\bar{\mathbf{3}}, \bar{\mathbf{3}}, \mathbf{1}) \oplus (\mathbf{1}, \mathbf{3}, \bar{\mathbf{3}})$$

## Overview of Group Theory

- The Cartan Classification of (compact) Lie Groups:

$$A_n \leftrightarrow SU(n+1), \quad B_n \leftrightarrow SO(2n+1),$$

$$C_n \leftrightarrow Sp(2n), \quad D_n \leftrightarrow SO(2n),$$

$$G_2, \quad F_4, \quad E_6, \quad E_7, \quad E_8.$$

- Let  $t_a$  be the generators of the Lie algebra associated with the Lie group. Then the Lie algebra is univocally defined by the structure constants  $f_{abc}$ .

$$[t_a, t_b] = f_{abc} t_c$$

- $A_n$  has  $n(n+2)$  generators,  $B_n$  and  $C_n$  have  $n(2n+1)$ ,  $D_n$  has  $n(2n-1)$  and the exceptional algebras,  $G_2, F_4, E_6, E_7$  and  $E_8$  have 14, 52, 78, 133 and 248 respectively.

- If we call  $h_i$  the maximal set of commuting generators, called the Cartan subalgebra, of size  $n$ , the rank of the group, such that

$$[h_i, h_j] = 0, \quad \forall i, j$$

- Let  $e_\alpha$  be the other generators, with  $e_{-\alpha} \equiv e_\alpha^\dagger$  and

$$[h_i, e_\alpha] = \alpha_i e_\alpha$$

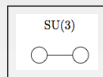
- The roots  $\alpha$  define the algebra. The minimum set of linearly independent roots, known as the simple roots, has size  $n$  and contains only positive roots.
- The last commutation relations are

$$[e_\alpha, e_{-\alpha}] = \alpha_i h_i, \quad [e_\alpha, e_\beta] = c_{\alpha, \beta} e_{\alpha+\beta} \quad \text{if } \alpha + \beta \neq 0$$

- The Cartan matrix (standard normalisation,  $\alpha \cdot \alpha = 2$ ), e.g.,  $A_2$

$$K(A_2) = \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix}$$

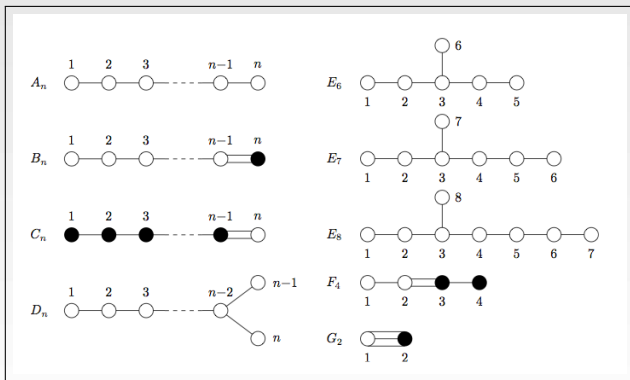
- The simple roots can be represented using **Dynkin diagrams**



- The dots represent the roots, black dots are shorter roots
- The links represent the angle between roots
  - 0 links  $\rightarrow \angle\{\alpha, \beta\} = \frac{\pi}{2}$
  - 1 link  $\rightarrow \angle\{\alpha, \beta\} = \frac{2\pi}{3}$
  - 2 links  $\rightarrow \angle\{\alpha, \beta\} = \frac{3\pi}{4}$
  - 3 links  $\rightarrow \angle\{\alpha, \beta\} = \frac{5\pi}{6}$



- The Dynkin diagrams for all simple groups are



- An  $n$ -dimensional **Representation** of the group is a set of  $n \times n$  matrices that act on an  $n$ -dimensional Hilbert space
- They satisfy the same commutation relations as the generators  $t_a$ .

$$[\mathcal{R}(t_a), \mathcal{R}(t_b)] = f_{abc} \mathcal{R}(t_c)$$

- The **weights** of the representation are the eigenvalues of the generators of the Cartan subalgebra on such Hilbert space

$$\mathcal{R}(h_i)|\lambda\rangle = w_i|\lambda\rangle$$

- There is a  $|\lambda\rangle$  such that  $\mathcal{R}(e_\alpha)|\lambda\rangle = 0$  for all the simple roots  $\alpha$ . Its weight is the **highest weight** and defines the representation, e.g.

$$w = (1, 1) \leftrightarrow \mathbf{8} \in SU(3)$$

- From the highest weight all weights can be obtain using  $\mathcal{R}(e_{-\alpha})$ , we obtain the **weight diagram**, e.g.

$$(1, 1) \quad (2, -1) \quad (0, 0) \quad (-2, 1) \quad (-1, -1) \\ (-1, 2) \quad (0, 0) \quad (1, -2)$$

- **Roots** define Simple Groups
  - A root system can be represented by a **Dynkin Diagram**
  - Non-simple groups are defined by the roots of its factors
  
- **Weights** define Representations
  - From the highest weight the **Weight Diagram** can be obtained

## Model Building: Groups and Representations

- Three main concepts from group theory:
  1. **Direct products of representations**  $\rightarrow$  invariants  
e.g.  $SU(5)$ ,

$$\mathbf{5} \otimes \bar{\mathbf{5}} = \mathbf{24} \oplus \mathbf{1}$$

2. **Subgroups of a group**  $\rightarrow$  breaking chains  
e.g.

$$E_6 \rightarrow SO(10) \rightarrow SU(5) \rightarrow SU(3)_c \times SU(2)_L \times U(1)_Y$$

3. **Decomposition of the representations**  $\rightarrow$  field content  
e.g.  $SO(10) \rightarrow SU(5) \times U(1)$

$$\mathbf{16} \rightarrow \mathbf{10}_{-1} \oplus \bar{\mathbf{5}}_3 \oplus \mathbf{1}_{-5}$$

- Three main concepts from group theory:
  1. **Direct products of representations**  $\rightarrow$  invariants  
e.g.  $SU(5)$ ,

$$\mathbf{5} \otimes \bar{\mathbf{5}} = \mathbf{24} \oplus \mathbf{1}$$

2. **Subgroups of a group**  $\rightarrow$  breaking chains  
e.g.

$$E_6 \rightarrow SO(10) \rightarrow SU(5) \rightarrow SU(3)_c \times SU(2)_L \times U(1)_Y$$

3. **Decomposition of the representations**  $\rightarrow$  field content  
e.g.  $SO(10) \rightarrow SU(5) \times U(1)$

$$\mathbf{16} \rightarrow \mathbf{10}_{-1} \oplus \bar{\mathbf{5}}_3 \oplus \mathbf{1}_{-5}$$

- The first case, the direct product of representations,

$$\mathcal{R}_1 \otimes \mathcal{R}_2 = \bigoplus_i \mathcal{R}_i$$

- Take each weight  $w_i$  from  $\mathcal{R}_1$  and each  $v_j$  from  $\mathcal{R}_2$
- The reducible representation  $\mathcal{R}_1 \otimes \mathcal{R}_2$  has weights  $w_i + v_j$ .
- Pick the highest weight from  $w_H \in w_i + v_j$  (most positive) that identifies a irrep
- Construct the weight diagram for  $w_H$  and take out those weights from  $w_i + v_j$
- Repeat until there is no more positive weights, leftovers will be  $(0, 0)$ , i.e., singlets



- An example, in  $SU(3)$ ,  $\mathbf{3} \otimes \bar{\mathbf{3}}$

$$\begin{array}{ccc} (1, 0) & (0, 1) & (1, 1)(2, -1)(0, 0) \\ (-1, 1) \otimes (1, -1) & = & (-1, 2)(0, 0)(-2, 1) \\ (0, -1) & (-1, 0) & (0, 0)(1, -2)(-1, -1) \end{array}$$

- An example, in  $SU(3)$ ,  $\mathbf{3} \otimes \bar{\mathbf{3}}$

$$\begin{array}{rcl}
 (1, 0) & (0, 1) & (1, 1)(2, -1)(0, 0) \\
 (-1, 1) \otimes (1, -1) & = & (-1, 2)(0, 0)(-2, 1) \\
 (0, -1) & (-1, 0) & (0, 0)(1, -2)(-1, -1)
 \end{array}$$

- An example, in  $SU(3)$ ,  $\mathbf{3} \otimes \bar{\mathbf{3}}$

$$\begin{array}{ccc}
 (1, 0) & (0, 1) & (1, 1)(2, -1)(0, 0) \\
 (-1, 1) \otimes (1, -1) & = & (-1, 2)(0, 0)(-2, 1) \\
 (0, -1) & (-1, 0) & (0, 0)(1, -2)(-1, -1)
 \end{array}$$

- The weight diagram obtained from  $(1, 1)$ , of dimension 8, is

$$(1, 1) \begin{array}{ccccc}
 (2, -1) & (0, 0) & (-2, 1) & & \\
 (-1, 2) & (0, 0) & (1, -2) & (-1, -1) & 
 \end{array}$$

- An example, in  $SU(3)$ ,  $\mathbf{3} \otimes \bar{\mathbf{3}}$

$$\begin{array}{ccc}
 (1, 0) & (0, 1) & (1, 1)(2, -1)(0, 0) \\
 (-1, 1) \otimes (1, -1) & = & (-1, 2)(0, 0)(-2, 1) \\
 (0, -1) & (-1, 0) & (0, 0)(1, -2)(-1, -1)
 \end{array}$$

- The weight diagram obtained from  $(1, 1)$ , of dimension 8, is

$$(1, 1) \quad (2, -1) \quad (0, 0) \quad (-2, 1) \quad (-1, -1) \\
 \quad \quad (-1, 2) \quad (0, 0) \quad (1, -2)$$

- An example, in  $SU(3)$ ,  $\mathbf{3} \otimes \bar{\mathbf{3}}$

$$\begin{array}{ccc}
 (1, 0) & (0, 1) & (1, 1)(2, -1)(0, 0) \\
 (-1, 1) \otimes (1, -1) & = & (-1, 2)(0, 0)(-2, 1) \\
 (0, -1) & (-1, 0) & (0, 0)(1, -2)(-1, -1)
 \end{array}$$

- The weight diagram obtained from  $(1, 1)$ , of dimension 8, is

$$\begin{array}{ccccc}
 (1, 1) & (2, -1) & (0, 0) & (-2, 1) & \\
 & (-1, 2) & (0, 0) & (1, -2) & (-1, -1)
 \end{array}$$

- The weight  $(0, 0)$  is just the singlet in  $SU(3)$ ,  $\mathbf{1}$

- An example, in  $SU(3)$ ,  $\mathbf{3} \otimes \bar{\mathbf{3}}$

$$\begin{array}{ccc}
 (1, 0) & (0, 1) & (1, 1)(2, -1)(0, 0) \\
 (-1, 1) \otimes (1, -1) & = & (-1, 2)(0, 0)(-2, 1) \\
 (0, -1) & (-1, 0) & (0, 0)(1, -2)(-1, -1)
 \end{array}$$

- The weight diagram obtained from  $(1, 1)$ , of dimension 8, is

$$\begin{array}{ccccc}
 (1, 1) & (2, -1) & (0, 0) & (-2, 1) & \\
 & (-1, 2) & (0, 0) & (1, -2) & (-1, -1)
 \end{array}$$

- The weight  $(0, 0)$  is just the singlet in  $SU(3)$ ,  $\mathbf{1}$
- So the result is

$$\mathbf{3} \otimes \bar{\mathbf{3}} = \mathbf{8} \oplus \mathbf{1}$$

- Three main concepts from group theory:
  1. **Direct products of representations**  $\rightarrow$  invariants  
e.g.  $SU(5)$ ,

$$5 \otimes \bar{5} = 24 \oplus 1$$

2. **Subgroups of a group**  $\rightarrow$  breaking chains  
e.g.

$$E_6 \rightarrow SO(10) \rightarrow SU(5) \rightarrow SU(3)_c \times SU(2)_L \times U(1)_Y$$

3. **Decomposition of the representations**  $\rightarrow$  field content  
e.g.  $SO(10) \rightarrow SU(5) \times U(1)$

$$16 \rightarrow 10_{-1} \oplus \bar{5}_3 \oplus 1_{-5}$$

- The maximal subgroups of a given group are of two types: **Regular Subgroups** and **Special Subgroups**.
- The **Regular maximal subgroups** can be calculated simply by removing a dot from the Dynkin diagram or the Extended Dynkin diagram.

e.g.

$$SU(5) \rightarrow SU(3) \times SU(2) \times U(1)$$

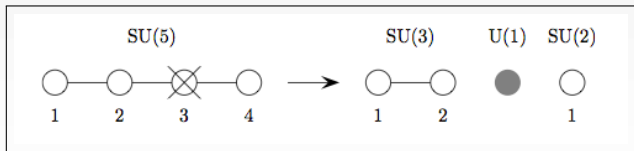
- The **Special maximal subgroups** must be obtained in a more heuristic way, by finding a group  $\mathcal{F} < \mathcal{G}$  for which there exists the decomposition  $\mathcal{R}(\mathcal{G}) \rightarrow \mathcal{R}(\mathcal{F})$ , e.g.,

$$\mathbf{7}(SO(7)) \rightarrow \mathbf{7}(G_2)$$

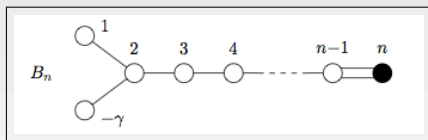


- The **Regular maximal subgroups** can be either semisimple or not, and the way of obtaining either is different
- Given the Dynkin diagram for a group, a **non-semisimple** subgroup can be obtained by simply eliminating a dot from the diagram
- The resulting disconnect diagrams correspond to the semi-simple part of the subgroup and the eliminated dot becomes the  $U(1)$  generator.

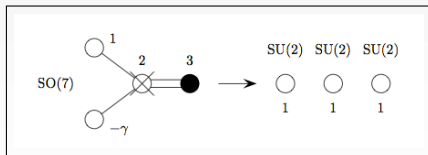
e.g.  $SU(5) \rightarrow SU(3) \times SU(2) \times U(1)$



- The **semisimple** groups are obtained by adding a root to the Dynkin diagram, to form the **Extended or Affine Dynkin Diagram**. This root,  $-\gamma$ , is the most negative root of the group, e.g. for  $B_n$ .



- For the example case  $B_3 \rightarrow A_1 \times A_1 \times A_1$ , eliminating the dot in the middle



- Through this procedure one can obtain all maximal subgroups of a given Lie Group
- To obtain all subgroups, one needs to iterate the procedure for the subgroups. This way the subgroups of  $SU(5)$  are

$$\begin{aligned}SU(5) \supset & SU(4) \times U(1), \\ & SU(3) \times SU(2) \times U(1), \\ & SU(3) \times U(1) \times U(1)^*, \\ & SU(2) \times SU(2) \times U(1) \times U(1)^*, \\ & SU(2) \times U(1) \times U(1) \times U(1)^*, \\ & U(1) \times U(1) \times U(1) \times U(1)^*.\end{aligned}$$

\* this subgroup is embedded into  $SU(5)$  in more than one way

- The final step while calculating the subgroups is the breaking of the **abelian factors**.
- Whenever there is more than one copy of  $U(1)$  the broken generator is a linear combination of the both generators, e.g.  $Y = I_{3R} + \frac{B-L}{2}$

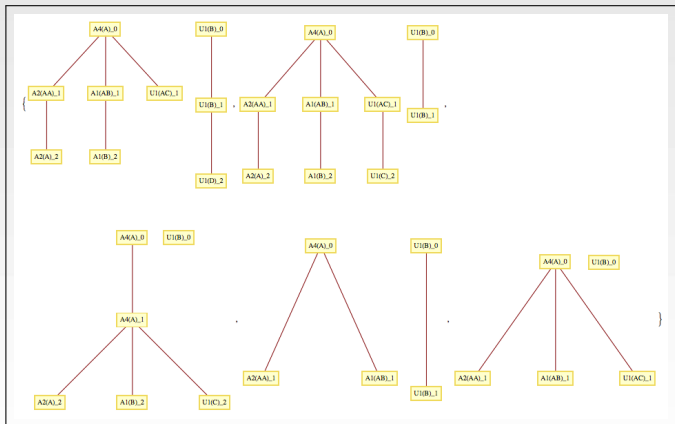
$$SU(3)_c \times SU(2)_L \times U(1)_R \times U(1)_{B-L} \rightarrow SU(3)_c \times SU(2)_L \times U(1)_Y$$

- Then, for the  $SU(5)$  example above, include the subgroups

$$\begin{aligned} SU(5) \supset & SU(4), SU(3) \times SU(2)^*, SU(3) \times U(1)^*, \\ & SU(3)^*, SU(2) \times SU(2) \times U(1)^*, \\ & SU(2) \times SU(2)^*, SU(2) \times U(1)^*, SU(2)^* \\ & U(1) \times U(1) \times U(1)^*, U(1) \times U(1)^*, U(1)^* \end{aligned}$$

- Breaking chains

e.g.,  $SU(5) \times U(1) \rightarrow SU(3) \times SU(2) \times U(1)$



- Three main concepts from group theory:
  1. **Direct products of representations**  $\rightarrow$  invariants  
e.g.  $SU(5)$ ,

$$\mathbf{5} \otimes \bar{\mathbf{5}} = \mathbf{24} \oplus \mathbf{1}$$

2. **Subgroups of a group**  $\rightarrow$  breaking chains  
e.g.

$$E_6 \rightarrow SO(10) \rightarrow SU(5) \rightarrow SU(3)_c \times SU(2)_L \times U(1)_Y$$

3. **Decomposition of the representations**  $\rightarrow$  field content  
e.g.  $SO(10) \rightarrow SU(5) \times U(1)$

$$\mathbf{16} \rightarrow \mathbf{10}_{-1} \oplus \bar{\mathbf{5}}_3 \oplus \mathbf{1}_{-5}$$

- The **Projection Matrix** projects the weights of a representation into weights of representations of the subgroup

$$P \cdot W = W'$$

- e.g. the decomposition of the  $\mathbf{5} \in SU(5)$  into irreps of  $SU(3) \times SU(2) \times U(1)$

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ \frac{1}{3} & \frac{2}{3} & 1 & \frac{1}{2} \end{pmatrix} \cdot \begin{pmatrix} 1 & -1 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 1 & -1 \end{pmatrix} = \begin{pmatrix} 1 & -1 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 & -1 \\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & -\frac{1}{2} & -\frac{1}{2} \end{pmatrix}$$

- So the decomposition goes:  $\mathbf{5} \rightarrow$

- The **Projection Matrix** projects the weights of a representation into weights of representations of the subgroup

$$P \cdot W = W'$$

- e.g. the decomposition of the  $\mathbf{5} \in SU(5)$  into irreps of  $SU(3) \times SU(2) \times U(1)$

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ \frac{1}{3} & \frac{2}{3} & 1 & \frac{1}{2} \end{pmatrix} \cdot \begin{pmatrix} 1 & -1 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 1 & -1 \end{pmatrix} = \begin{pmatrix} 1 & -1 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 & -1 \\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & -\frac{1}{2} & -\frac{1}{2} \end{pmatrix}$$

- So the decomposition goes:  $\mathbf{5} \rightarrow (\mathbf{3}, \mathbf{1})_{\frac{1}{3}}$



- The **Projection Matrix** projects the weights of a representation into weights of representations of the subgroup

$$P \cdot W = W'$$

- e.g. the decomposition of the  $\mathbf{5} \in SU(5)$  into irreps of  $SU(3) \times SU(2) \times U(1)$

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ \frac{1}{3} & \frac{2}{3} & 1 & \frac{1}{2} \end{pmatrix} \cdot \begin{pmatrix} 1 & -1 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 1 & -1 \end{pmatrix} = \begin{pmatrix} 1 & -1 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 & -1 \\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & -\frac{1}{2} & -\frac{1}{2} \end{pmatrix}$$

- So the decomposition goes:  $\mathbf{5} \rightarrow (\mathbf{3}, \mathbf{1})_{\frac{1}{3}} \oplus (\mathbf{1}, \mathbf{2})_{-\frac{1}{2}}$

- The projection matrices are calculated at the time of obtaining the subgroups
- For **non-semisimple** subgroups, simply move the element of weights corresponding to the eliminated dot to the end and substitute every element by the dual of the weight it belongs to

$$W = \begin{pmatrix} 1 & -1 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 1 & -1 \end{pmatrix}, \quad W' = \begin{pmatrix} 1 & -1 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 & -1 \\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & -\frac{1}{2} & -\frac{1}{2} \end{pmatrix}$$

- And thus  $P = W' \cdot W^{-1}$ , where  $W^{-1}$  is the *pseudoinverse* of  $W$ , and we obtain the projection matrix from before

$$P = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ \frac{1}{3} & \frac{2}{3} & 1 & \frac{1}{2} \end{pmatrix}$$

- In the case of **semisimple** subgroups, add an element to every weight corresponding to the product  $\alpha \cdot \gamma$ , and then remove an element of every weight corresponding to the eliminated dot in the diagram
- e.g, for the case of  $SO(7)$ , the generating rep is the **8**, whose weight matrix is

$$w = \begin{pmatrix} 0 & 0 & 1 & -1 & 1 & -1 & 0 & 0 \\ 0 & 1 & -1 & 0 & 0 & 1 & -1 & 0 \\ 1 & -1 & 1 & 1 & -1 & -1 & 1 & -1 \end{pmatrix}$$

- Now, adding the extended root,  $-\gamma$ , and dropping the second dot, to give  $SU(2) \times SU(2) \times SU(2)$

$$w' = \begin{pmatrix} 0 & 0 & 1 & -1 & 1 & -1 & 0 & 0 \\ -1 & -1 & 0 & 0 & 0 & 0 & 1 & 1 \\ 1 & -1 & 1 & 1 & -1 & -1 & 1 & -1 \end{pmatrix}$$

- Which can be identified as  $\mathbf{8} = (\mathbf{2}, \mathbf{1}, \mathbf{2}) \oplus (\mathbf{1}, \mathbf{2}, \mathbf{2})$ , and

$$P = w' \cdot w^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ -1 & -2 & -1 \\ 0 & 0 & 1 \end{pmatrix}$$

## Model Building: Theories and Models

- In order to build a model, we start with the minimal inputs

$$\{\mathcal{G}, \mathcal{R}_1, \mathcal{R}_2 \dots\}$$

- We obtain the breaking chains of  $\mathcal{G}$  to the SM

$$\mathcal{G} \rightarrow \mathcal{G}_1 \rightarrow \mathcal{G}_2 \rightarrow \dots \rightarrow \mathcal{G}_n \rightarrow \mathcal{G}_{SM}$$

- For all possible chains, we choose one path and we build all possible model that spawn from it and check their viability.
- One can iterate over all possible breaking chains to consider all models given by the pair Group + Reprs.

- For a particular path, we can define a **Theory** as a set containing a *Lie Group*, a list of *Reps* of the group and a *Breaking Chain*, e.g.

$$\begin{aligned} \{\mathcal{G} &= SU(5) \times U(1), \\ \mathcal{R} &= \mathbf{10}_{-1} \oplus \bar{\mathbf{5}}_3 \oplus \mathbf{5}_2, \\ SU(5) \times U(1) &\rightarrow SU(3) \times SU(2) \times U(1)\} \end{aligned}$$

- We define then a **Model** as a list of Theories, one per step on the breaking chain, e.g.

$$\left\{ \begin{array}{l} \mathcal{G} = SU(5) \times U(1), \\ \mathcal{R} = \mathbf{10}_{-1} \oplus \bar{\mathbf{5}}_3 \oplus \mathbf{5}_2, \\ SU(5) \times U(1) \rightarrow \\ \rightarrow SU(3) \times SU(2) \times U(1) \end{array} \right\} \left\{ \begin{array}{l} \mathcal{G} = SU(3) \times SU(2) \times U(1), \\ \mathcal{R} = (\mathbf{3}, \mathbf{2})_{\frac{1}{6}} \oplus (\bar{\mathbf{3}}, \mathbf{1})_{-\frac{2}{3}} \oplus (\bar{\mathbf{3}}, \mathbf{1})_{\frac{1}{3}} \oplus \\ (\mathbf{1}, \mathbf{2})_{-\frac{1}{2}} \oplus (\mathbf{1}, \mathbf{1})_1 \oplus (\mathbf{1}, \mathbf{2})_{\frac{1}{2}} \oplus (\mathbf{3}, \mathbf{1})_{-\frac{1}{3}} \\ SU(3) \times SU(2) \times U(1) \rightarrow \{\} \end{array} \right\}$$

- For a particular path, we can define a **Theory** as a set containing a *Lie Group*, a list of *Reps* of the group and a *Breaking Chain*, e.g.

$$\begin{aligned} \{\mathcal{G} &= SU(5) \times U(1), \\ \mathcal{R} &= \mathbf{10}_{-1} \oplus \bar{\mathbf{5}}_3 \oplus \mathbf{5}_2, \\ SU(5) \times U(1) &\rightarrow SU(3) \times SU(2) \times U(1)\} \end{aligned}$$

- We define then a **Model** as a list of Theories, one per step on the breaking chain, e.g.

$$\left\{ \begin{array}{l} \mathcal{G} = SU(5) \times U(1), \\ \mathcal{R} = \mathbf{10}_{-1} \oplus \bar{\mathbf{5}}_3 \oplus \mathbf{5}_2, \quad \times 3 \\ SU(5) \times U(1) \rightarrow \\ \rightarrow SU(3) \times SU(2) \times U(1) \end{array} \right\} \left\{ \begin{array}{l} \mathcal{G} = SU(3) \times SU(2) \times U(1), \\ \mathcal{R} = (\mathbf{3}, \mathbf{2})_{\frac{1}{6}} \oplus (\bar{\mathbf{3}}, \mathbf{1})_{-\frac{2}{3}} \oplus (\bar{\mathbf{3}}, \mathbf{1})_{\frac{1}{3}} \oplus \quad \times 3 \\ (\mathbf{1}, \mathbf{2})_{-\frac{1}{2}} \oplus (\mathbf{1}, \mathbf{1})_1 \oplus (\mathbf{1}, \mathbf{2})_{\frac{1}{2}} \oplus (\mathbf{3}, \mathbf{1})_{-\frac{1}{3}} \\ SU(3) \times SU(2) \times U(1) \rightarrow \{\} \end{array} \right\}$$

- Not every model will be a successful model
- One needs to impose a set of constraints
  1. **Anomaly free** and must satisfy **charge conservation**

$$\sum_i \mathcal{A}(\mathcal{R}_i) = 0, \quad \sum_i Q(\mathcal{R}_i) = 0$$

2. **Symmetry breaking** required by the chain must happen

$$H \rightarrow (\mathbf{1}, \mathbf{2})_{-\frac{1}{2}} \left( H_2 \rightarrow (\mathbf{1}, \mathbf{2})_{\frac{1}{2}} \right)$$

3. The field content at the lowest step should be the **Standard Model field content** (singlets)

$$Q \rightarrow (\mathbf{3}, \mathbf{2})_{\frac{1}{6}}, \quad \bar{u} \rightarrow (\bar{\mathbf{3}}, \mathbf{1})_{-\frac{2}{3}}, \quad \bar{d} \rightarrow (\bar{\mathbf{3}}, \mathbf{1})_{\frac{1}{3}},$$

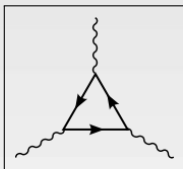
$$L \rightarrow (\mathbf{1}, \mathbf{2})_{-\frac{1}{2}}, \quad \bar{e} \rightarrow (\mathbf{1}, \mathbf{1})_1, \quad (\times 3)$$

4. **Chirality** must be satisfied



- To make sure that **only the SM survives at the EW scale**, one needs to integrate out any exotic field content at higher energies
- As a requirement for symmetry breaking, all gauge boson are assumed to acquire masses of the order of the symmetry at which they decouple  $M_X \sim v$
- Keeping the SM field content aside, we will generate all the possible models where the exotic fields are integrated out at the different scales of the model
- For every such model, we will check for the constraints above to classify it as valid or not

- Gauge **Anomalies** arise whenever one-loop triangle diagrams do not cancel



$$\text{Tr}\{t_{\mathcal{R}}^a, t_{\mathcal{R}}^b\}t_{\mathcal{R}}^c = \mathcal{A}(\mathcal{R})d^{abc}$$

- In general, only  $SU(N)$ ,  $N \geq 3$  and  $E_6$  suffer from this anomalies. For those cases, the field content must be such that makes the theory anomaly free, using the properties

$$\mathcal{A}(\mathcal{R}_1 \oplus \mathcal{R}_2) = \mathcal{A}(\mathcal{R}_1) + \mathcal{A}(\mathcal{R}_2), \quad \mathcal{A}(\bar{\mathcal{R}}) = -\mathcal{A}(\mathcal{R}), \quad \mathcal{A}(\mathbf{1}) = 0$$

- e.g. for the case of  $SU(5)$ , it turns out that  $\mathcal{A}(\mathbf{10} \oplus \bar{\mathbf{5}}) = 0$ , so the matter field content is anomaly free

- Anomaly cancellation in the case of  $U(1)$  implies **charge conservation**, which means that for every abelian factor  $U(1)_j$ , one needs that

$$\sum_i Q_j(\mathcal{R}_i) = 0$$

where  $Q$  are the  $U(1)$  charges, weighted by  $d(\mathcal{R}_i)$ .

- Thus, for the  $SU(5) \times U(1)$  model above, one needs to add an extra  $\mathbf{1}_{-5}$ , for this to happen
- The last anomaly is the **Witten anomaly**, which has to do with the topology of  $SU(2)$ , and is avoided whenever there is an even number of  $SU(2)$  fermion doublets, as in the SM

- **Spontaneous symmetry breaking** from one step of the chain to another must happen whenever a scalar field gets a vacuum expectation value
- At this stage we do not worry about the scalar potential, we assume that if such field exists, there is a suitable potential that is unstable at  $\phi = 0$  at some breaking scale

$$\left. \frac{\partial V}{\partial \phi} \right|_{\phi=v} = 0, \quad \left. \frac{\partial^2 V}{\partial \phi^2} \right|_{\phi=v} > 0, \quad \langle \phi \rangle = v \neq 0$$

- We then impose that in order to break  $\mathcal{G} \rightarrow \mathcal{F}$ , there must be a non-singlet field  $\phi \in \mathcal{G}$  that contains a singlet when decomposed under  $\mathcal{F}$ ,  $\mathbf{1} \in \phi|_{\mathcal{F}}$

- At every step, we check that there is one such field  $\phi$ , and if so, we only keep the model that integrates out the singlet component at that step
- The rest of the components of  $\phi$  may be integrated out or not, there could be mass splitting among components
- For the case of  $SU(5) \times U(1) \rightarrow SU(3) \times SU(2) \times U(1)$ , one could add  $\phi \rightarrow \mathbf{24}_X$ , with  $X \neq 0$ , which decomposes

$$\mathbf{24}_X \rightarrow (\mathbf{8}, \mathbf{1})_X \oplus (\mathbf{1}, \mathbf{3})_X \oplus (\mathbf{3}, \mathbf{2})_{X+1} \oplus (\bar{\mathbf{3}}, \mathbf{2})_{X-1} \oplus (\mathbf{1}, \mathbf{1})_X$$

- So adding that representation to the field content and giving a v.e.v. to the singlet component would trigger the symmetry breaking

- With all this, one can make a realistic model from the example above

$$\left\{ \begin{array}{l} \mathcal{G} = SU(5) \times U(1), \\ \mathcal{R} = \mathbf{10}_{-1} \oplus \bar{\mathbf{5}}_3 \oplus \mathbf{5}_2, \quad \times 3 \\ \\ SU(5) \times U(1) \rightarrow \\ \quad \rightarrow SU(3) \times SU(2) \times U(1) \end{array} \right\} \left| \begin{array}{l} \mathcal{G} = SU(3) \times SU(2) \times U(1), \\ \mathcal{R} = (\mathbf{3}, \mathbf{2})_{\frac{1}{6}} \oplus (\bar{\mathbf{3}}, \mathbf{1})_{-\frac{2}{3}} \oplus (\bar{\mathbf{3}}, \mathbf{1})_{\frac{1}{3}} \oplus \quad \times 3 \\ \quad (\mathbf{1}, \mathbf{2})_{-\frac{1}{2}} \oplus (\mathbf{1}, \mathbf{1})_1 \oplus (\mathbf{1}, \mathbf{2})_{\frac{1}{2}} \oplus (\mathbf{3}, \mathbf{1})_{-\frac{1}{3}} \\ \\ SU(3) \times SU(2) \times U(1) \rightarrow \{\} \end{array} \right.$$

- With all this, one can make a realistic model from the example above

$$\left\{ \begin{array}{l} \mathcal{G} = SU(5) \times U(1), \\ \mathcal{R} = \mathbf{10}_{-1} \oplus \bar{\mathbf{5}}_3 \oplus \mathbf{5}_2, \quad \times 3 \\ \\ SU(5) \times U(1) \rightarrow \\ \rightarrow SU(3) \times SU(2) \times U(1) \end{array} \right. \left| \begin{array}{l} \mathcal{G} = SU(3) \times SU(2) \times U(1), \\ \mathcal{R} = (\mathbf{3}, \mathbf{2})_{\frac{1}{6}} \oplus (\bar{\mathbf{3}}, \mathbf{1})_{-\frac{2}{3}} \oplus (\bar{\mathbf{3}}, \mathbf{1})_{\frac{1}{3}} \oplus \quad \times 3 \\ (\mathbf{1}, \mathbf{2})_{-\frac{1}{2}} \oplus (\mathbf{1}, \mathbf{1})_1 \oplus (\mathbf{1}, \mathbf{2})_{\frac{1}{2}} \oplus (\mathbf{3}, \mathbf{1})_{-\frac{1}{3}} \\ \\ SU(3) \times SU(2) \times U(1) \rightarrow \{\} \end{array} \right.$$

- Include **3** generations of matter fields to reproduce the SM field content

- With all this, one can make a realistic model from the example above

$$\left\{ \begin{array}{l} \mathcal{G} = SU(5) \times U(1), \\ \mathcal{R} = \mathbf{10}_{-1} \oplus \bar{\mathbf{5}}_3 \oplus \mathbf{5}_2 \oplus \mathbf{1}_{-5} \oplus \bar{\mathbf{5}}_{-2} \\ SU(5) \times U(1) \rightarrow \\ \rightarrow SU(3) \times SU(2) \times U(1) \end{array} \right. \times 3 \quad \left\{ \begin{array}{l} \mathcal{G} = SU(3) \times SU(2) \times U(1), \\ \mathcal{R} = (\mathbf{3}, \mathbf{2})_{\frac{1}{6}} \oplus (\bar{\mathbf{3}}, \mathbf{1})_{-\frac{2}{3}} \oplus (\bar{\mathbf{3}}, \mathbf{1})_{\frac{1}{3}} \oplus (\mathbf{1}, \mathbf{2})_{-\frac{1}{2}} \oplus (\mathbf{1}, \mathbf{1})_1 \oplus (\mathbf{1}, \mathbf{2})_{\frac{1}{2}} \oplus (\mathbf{3}, \mathbf{1})_{-\frac{1}{3}} \\ (SU(3) \times SU(2) \times U(1)) \rightarrow \{ \end{array} \right. \times 3$$

- Include **3** generations of matter fields to reproduce the SM field content
- Add a singlet,  $\mathbf{1}_{-5}$  to ensure charge quantisation, and a fiveplet,  $\bar{\mathbf{5}}_{-2}$  for anomaly cancellation



- With all this, one can make a realistic model from the example above

$$\left\{ \begin{array}{l} \mathcal{G} = SU(5) \times U(1), \\ \mathcal{R} = \mathbf{10}_{-1} \oplus \bar{\mathbf{5}}_3 \oplus \mathbf{5}_2 \oplus \\ \quad \mathbf{1}_{-5} \oplus \bar{\mathbf{5}}_{-2} \oplus \mathbf{24}_X \\ SU(5) \times U(1) \rightarrow \\ \quad \rightarrow SU(3) \times SU(2) \times U(1) \end{array} \right. \times 3 \left\{ \begin{array}{l} \mathcal{G} = SU(3) \times SU(2) \times U(1), \\ \mathcal{R} = (\mathbf{3}, \mathbf{2})_{\frac{1}{6}} \oplus (\bar{\mathbf{3}}, \mathbf{1})_{-\frac{2}{3}} \oplus (\bar{\mathbf{3}}, \mathbf{1})_{\frac{1}{3}} \oplus \\ \quad (\mathbf{1}, \mathbf{2})_{-\frac{1}{2}} \oplus (\mathbf{1}, \mathbf{1})_1 \oplus (\mathbf{1}, \mathbf{2})_{\frac{1}{2}} \oplus (\mathbf{3}, \mathbf{1})_{-\frac{1}{3}} \\ \quad (\mathbf{1}, \mathbf{1})_0 \oplus (\bar{\mathbf{3}}, \mathbf{1})_{\frac{1}{3}} \oplus (\mathbf{1}, \mathbf{2})_{-\frac{1}{2}} \oplus \dots \\ SU(3) \times SU(2) \times U(1) \rightarrow \{ \} \end{array} \right. \times 3$$

- Include **3** generations of matter fields to reproduce the SM field content
- Add a singlet,  $\mathbf{1}_{-5}$  to ensure charge quantisation, and a fiveplet,  $\bar{\mathbf{5}}_{-2}$  for anomaly cancellation
- Add a scalar  $\mathbf{24}_X$  to ensure symmetry breaking

- With all this, one can make a realistic model from the example above

$$\left\{ \begin{array}{l} \mathcal{G} = SU(5) \times U(1), \\ \mathcal{R} = \mathbf{10}_{-1} \oplus \bar{\mathbf{5}}_3 \oplus \mathbf{5}_2 \oplus, \quad \times 3 \\ \quad \mathbf{1}_{-5} \oplus \bar{\mathbf{5}}_{-2} \oplus \mathbf{24}_X \\ SU(5) \times U(1) \rightarrow \\ \quad \rightarrow SU(3) \times SU(2) \times U(1) \end{array} \right\} \left\{ \begin{array}{l} \mathcal{G} = SU(3) \times SU(2) \times U(1), \\ \mathcal{R} = (\mathbf{3}, \mathbf{2})_{\frac{1}{6}} \oplus (\bar{\mathbf{3}}, \mathbf{1})_{-\frac{2}{3}} \oplus (\bar{\mathbf{3}}, \mathbf{1})_{\frac{1}{3}} \oplus \quad \times 3 \\ \quad (\mathbf{1}, \mathbf{2})_{-\frac{1}{2}} \oplus (\mathbf{1}, \mathbf{1})_1 \oplus (\mathbf{1}, \mathbf{2})_{\frac{1}{2}} \oplus (\mathbf{3}, \mathbf{1})_{-\frac{1}{3}} \\ \quad (\mathbf{1}, \mathbf{1})_0 \\ SU(3) \times SU(2) \times U(1) \rightarrow \{\} \end{array} \right\}$$

- Include **3** generations of matter fields to reproduce the SM field content
- Add a singlet,  $\mathbf{1}_{-5}$  to ensure charge quantisation, and a fiveplet,  $\bar{\mathbf{5}}_{-2}$  for anomaly cancellation
- Add a scalar  $\mathbf{24}_X$  to ensure symmetry breaking
- Integrate out all exotic fields (except maybe the singlet)

- To summarise, the process of generating models goes like this
  1. First, given a **theory**, calculate the **full model**, with all irreps at all scales
  2. Start at the **second-to-highest scale**
  3. Generate of **possible combinations** of non-SM representations, including the case with **all** of them and the case with **none**
  4. For every combination, create the corresponding **model**
  5. Check if the model is **valid** with respect to the constraints
  6. If the model is valid, move to the **next scale**, and go back to step **3**
  7. If at the low scale any of the constraints are **not satisfied** it will feed back to the high scale and exclude that model
- **In the end, we will have a list of models that satisfy all the imposed constraints**

## Conclusions and Applications

- A result of the model building tool is the **RGE running of the gauge couplings** (at one-loop level)
- At every step they only depend on group parameters, such as the **Casimir** of the group and the **Dynkin Index** of the representations involved,

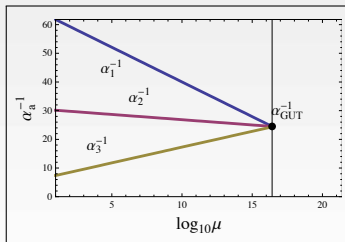
$$\begin{aligned}\beta_{g_a} &= (\sum_i \mathcal{I}(\mathcal{R}_i) - 3\mathcal{C}(\mathcal{G}_a))g_a^3, && \text{SUSY} \\ \beta_{g_a} &= (\frac{2}{3} \sum_{i \in F} \mathcal{I}(\mathcal{F}_i) + \frac{1}{3} \sum_{i \in S} \mathcal{I}(\mathcal{S}_i) - \frac{11}{3}\mathcal{C}(\mathcal{G}_a))g_a^3 && \text{Non-SUSY}\end{aligned}$$

- With the SM gauge couplings as the low energy fixed points, the running of the couplings and the intermediate scales can be obtained by satisfying the relevant boundary conditions

- Applications of this include both **Supersymmetric** and **Non-Supersymmetric** Grand Unified Models
- It can potentially deal with models in which **Supersymmetry breaking** happens at any scale, since the effect would be to integrate out the Supersymmetric partners at the scale of SUSY breaking
- Three example cases of model are given
  1. **A minimal Supersymmetric  $SO(10)$  model, with minimal Higgs content and direct breaking to the Standard Model**
  2. **A non-supersymmetric,  $SO(10)$  inspired, left-right symmetry model**
  3. **A model of GUT scale, hybrid inflation, with an  $SU(5) \times U(1)$  intermediate waterfall breaking**

- Minimal Supersymmetric  $SO(10)$  model

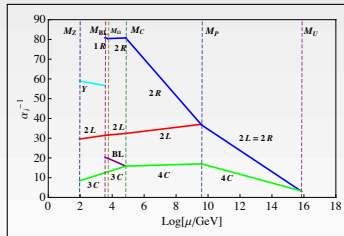
$$\left\{ \begin{array}{l} \mathcal{G} = SO(10), \\ \mathcal{R} = \mathbf{16} \oplus \mathbf{16} \oplus \mathbf{16} \oplus \mathbf{10} \oplus \mathbf{144} \\ \\ SO(10) \rightarrow SU(3) \times SU(2) \times U(1) \end{array} \right\} \left\{ \begin{array}{l} \mathcal{G} = SU(3) \times SU(2) \times U(1), \\ \mathcal{R} = (\mathbf{3}, \mathbf{2})_{\frac{1}{6}} \oplus (\bar{\mathbf{3}}, \mathbf{1})_{-\frac{2}{3}} \oplus (\bar{\mathbf{3}}, \mathbf{1})_{\frac{1}{3}} \oplus \\ (\mathbf{1}, \mathbf{2})_{-\frac{1}{2}} \oplus (\mathbf{1}, \mathbf{1})_1 \oplus \\ (\mathbf{1}, \mathbf{2})_{\frac{1}{2}} \oplus (\mathbf{1}, \mathbf{2})_{-\frac{1}{2}} \\ SU(3) \times SU(2) \times U(1) \rightarrow \{ \} \end{array} \right\} \times 3$$



F.Deppisch, N.Desai, T.G. [Front.Phys. 2 (2014) 00027]

- Non-SUSY Left-Right Symmetry model

$$\begin{aligned}
 SO(10) &\rightarrow SU(4) \times SU(2) \times SU(2) \times D \quad \rightarrow SU(4) \times SU(2) \times SU(2) \\
 &\rightarrow SU(3) \times SU(2) \times SU(2) \times U(1) \rightarrow SU(3) \times SU(2) \times U(1) \times U(1) \\
 &\rightarrow SU(3) \times SU(2) \times U(1)
 \end{aligned}$$



F.Deppisch, T.G., S.Patra, N.Sahu, U.Sarkar [Phys. Rev. D 90, 053014]  
 F.Deppisch, T.G., S.Patra, N.Sahu, U.Sarkar [pending publication]



- **GUT scale, hybrid inflation, with an  $SU(5) \times U(1)$  intermediate waterfall breaking**

$$\mathbf{16}_F^3, \mathbf{16}_H, \bar{\mathbf{16}}_H, \mathbf{45}_H, \mathbf{45}_H, \mathbf{10}_H$$

$$SO(10) \times U(1) \rightarrow SU(5) \times U(1) \rightarrow SU(3) \times SU(2) \times U(1)$$

J.Ellis, T.G., J. Harz, W-C.Huang [in progress]

Thank you!

- Properties of groups
- Metric of the group

$$G_{ij} = K_{ij}^{-1} \frac{(\alpha_j, \alpha_j)}{2}$$

- Product of roots

$$(\alpha, \beta) = \sum_{i,j} \alpha_i G_{ij} \beta_j$$

- Dual of a root

$$\alpha_i^* = G_{ij} \alpha_j$$

- Properties of representations
- Dimension of an irrep

$$d(\mathcal{R}) = \prod_{\alpha} \frac{\alpha \cdot (\Lambda + \delta)}{\alpha \cdot \delta}$$

where  $\Lambda$  is the highest weight of the irrep.

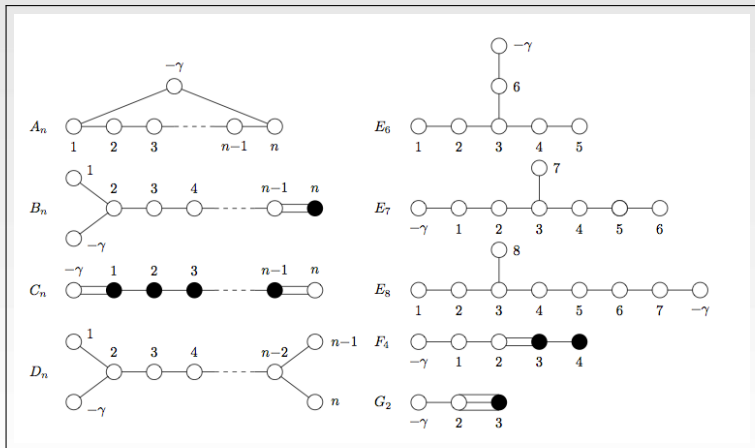
- The Casimir of a representation is defined as

$$\mathcal{C}(\mathcal{R}) = \text{Tr} t_a t_a = \Lambda \cdot (\Lambda + 2\delta)$$

- And the Dynkin Index of the representation

$$\mathcal{I}(\mathcal{R}) = \frac{d(\mathcal{R})}{d(\mathcal{G})} \mathcal{C}(\mathcal{R})$$

- Extended Dynkin diagrams



- Definition of pseudo inverse
- For a non-square matrix,  $n \times m$ ,  $A$  the pseudo inverse can be define such that

$$\tilde{A}^{-1} \equiv A^T \cdot (A \cdot A^T)^{-1}$$

so that

$$A \cdot \tilde{A}^{-1} = I_n$$